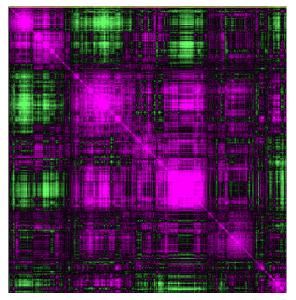
Practical Bioinformatics

Mark Voorhies

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Clustering exercises – Visualizing the distance matrix



Fun with logarithms

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$$\log(xy) = \log(x) + \log(y)$$
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Also, we can change of the base of a logarithm like so:

$$\log_A(x) = \log(x)/\log(A)$$



Dictionaries

```
\begin{array}{ll} \mbox{dictionary} &= \{ \mbox{"A"} : \mbox{"T"} , \mbox{"T"} : \mbox{"A"} , \mbox{"G"} : \mbox{"C"} , \mbox{"C"} : \mbox{"G"} \} \\ \mbox{dictionary} \left[ \mbox{"N"} \right] &= \mbox{"N"} \\ \mbox{dictionary} : \mbox{has} \mbox{key} \left( \mbox{"C"} \right) \end{array}
```

Dictionaries

```
geneticCode = {"TTT":"F"."TTC":"F"."TTA":"L"."TTG":"L".
                  .
"CTT" : "L" ."CTC" : "L" ."CTA" : "L" ."CTG" : "L" .
                  "ATT":" I", "ATC":" I", "ATA":" I", "ATG":"M",
                  "GTT":"V"."GTC":"V","GTA":"V","GTG":"V",
                  "TCT": "S", "TCC": "S", "TCA": "S", "TCG": "S",
                 "CCT":"P","CCC":"P","CCA":"P","CCG":"P",
"ACT":"T","ACC":"T","ACA":"T","ACG":"T",
                  "GCT": "A", "GCC": "A", "GCA": "A", "GCG": "A",
                  "TAT": "Y". "TAC": "Y". "TAA": "*". "TAG": "*".
                  "CAT": "H". "CAC": "H". "CAA": "Q". "CAG": "Q".
                  "AAT": "N". "AAC": "N", "AAA": "K", "AAG": "K",
                  "GAT": "D". "GAC": "D". "GAA": "E". "GAG": "E".
                  "TGT": "C", "TGC": "C", "TGA": "*", "TGG": "W",
                  "CGT": "R", "CGC": "R", "CGA": "R", "CGG": "R",
                  "AGT": "S". "AGC": "S". "AGA": "R". "AGG": "R".
                  "GGT": "G", "GGC": "G", "GGA": "G", "GGG": "G"}
```

Homework choice 1: Dictionaries

- Write a function to return the antisense strand of a DNA sequence in 3'→5' orientation.
- ② Write a function to return the complement of a DNA sequence in $5'\rightarrow 3'$ orientation.
- Write a function to translate a DNA sequence

Homework choice 2: Linear Algebra

1 A two dimensional rotation, counterclockwise around the origin by θ , can be written as

$$\begin{pmatrix}
\cos\theta & -\sin\theta \\
\sin\theta & \cos\theta
\end{pmatrix}$$

Try implementing rotations via numpy's dot function. *E.g.*, plot a set of two dimensional points, then rotate them and plot the new coordinates in a different color.

$$\begin{bmatrix} \cos 90^{\circ} & \sin 90^{\circ} \\ -\sin 90^{\circ} & \cos 90^{\circ} \end{bmatrix} \begin{bmatrix} \alpha_{1} \\ \alpha_{2} \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$$